

Reflection Matrices

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Suppose we want a reflection across the line
 $l: ax+by=0$

We can characterize such a reflection by a matrix S_l which does the following:

If \vec{v}_{\parallel} is a vector parallel to l : $S_l \vec{v}_{\parallel} = \vec{v}_{\parallel}$

If \vec{v}_{\perp} is a vector perpendicular to l : $S_l \vec{v}_{\perp} = -\vec{v}_{\perp}$

Fact: If $\vec{v} \cdot \vec{w} = 0$, then $\vec{v} \perp \vec{w}$

If $\vec{w} = \begin{pmatrix} x \\ y \end{pmatrix}$ is a point on l , then notice that

$$0 = ax + by = \begin{pmatrix} a \\ b \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

so that $\begin{pmatrix} a \\ b \end{pmatrix}$ is perpendicular to \vec{w} , i.e., $\vec{v}_{\perp} = \begin{pmatrix} a \\ b \end{pmatrix}$.

Then, we can find a parallel vector to be $\vec{v}_{\parallel} = \begin{pmatrix} b \\ -a \end{pmatrix}$.

One can also use that $\vec{v}_{\parallel} = \begin{pmatrix} \text{run} \\ \text{rise} \end{pmatrix}$, where $\frac{\text{rise}}{\text{run}}$ is the slope of l . Then we can construct \vec{v}_{\perp} by doing the same for a line perpendicular to l .

We need to construct the S_L described above. (30)

We have 2 tools:

i) Creating matrices which send \hat{i} & \hat{j} wherever we want.

ii) Inverting matrices.

Creating S_L

Step 1: Create a matrix C such that

$$C\hat{i} = \vec{v}_\perp \quad \& \quad C\hat{j} = \vec{v}_\parallel \quad (\text{or the other way, if you like}).$$

$$\text{Thus } C = (C\hat{i} \quad C\hat{j}) = \begin{pmatrix} a & b \\ b & -a \end{pmatrix}$$

Step 2: Find C^{-1}

$$C^{-1} = \frac{1}{-a^2 - b^2} \begin{pmatrix} -a & -b \\ -b & a \end{pmatrix} = \frac{1}{a^2 + b^2} \begin{pmatrix} a & b \\ b & -a \end{pmatrix}$$

Notice that $C^{-1}\vec{v}_\perp = \hat{i}$ & $C^{-1}\vec{v}_\parallel = \hat{j}$.

So, after using C^{-1} , we can work with \hat{i} & \hat{j} .

Step 3: Create a matrix F such that

$$F\hat{i} = -\hat{i} \quad \& \quad F\hat{j} = \hat{j}$$

Since $\hat{i} \leftrightarrow \vec{v}_\perp$, we want to flip it.

$$F = (F\hat{i} \quad F\hat{j}) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

Step 4: Create S_ℓ .

After doing C^{-1} , then F , we undo C^{-1} by applying C . Then $S_\ell = CFC^{-1}$.

proof: $S_\ell \vec{v}_\parallel = CFC^{-1}\vec{v}_\parallel = CF\hat{j} = C\hat{j} = \vec{v}_\parallel$

$$S_\ell \vec{v}_\perp = CFC^{-1}\vec{v}_\perp = CF\hat{i} = C(-\hat{i}) = -C\hat{i} = -\vec{v}_\perp$$

If we multiply out CFC^{-1} , we find

$$S_\ell = \frac{1}{a^2+b^2} \begin{pmatrix} -a^2+b^2 & -2ab \\ -2ab & a^2-b^2 \end{pmatrix}$$

Ex: Find a matrix for the reflection about the line
line ^(a) $x=0$ ^(b) $2x-y=0$

Sol: (a) It's easy to see that we can choose

$$\vec{v}_{\parallel} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \hat{j} \quad \& \quad \vec{v}_{\perp} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hat{i}$$

$$\text{Then } C = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \& \quad C^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\text{Thus } S_{\{x=0\}} = C^{-1}FC = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

This should make sense since we can see that

$$\begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{pmatrix} -x \\ y \end{pmatrix} \quad \text{under this reflection}$$

and

$$S_{\{x=0\}} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -x \\ y \end{pmatrix}$$

(b) Here $a=2$, $b=-1$, so

$$S_{2x-y=0} = \frac{1}{4+1} \begin{pmatrix} -4+1 & 4 \\ 4 & 4-1 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} -3 & 4 \\ 4 & 3 \end{pmatrix} = \begin{pmatrix} -3/5 & 4/5 \\ 4/5 & 3/5 \end{pmatrix}$$

An alternate characterization of reflections

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Suppose the line l makes an angle Ψ with the positive x -axis, then the reflection about l can be written as

$$S_l = S_\Psi = \begin{pmatrix} \cos 2\Psi & \sin 2\Psi \\ \sin 2\Psi & -\cos 2\Psi \end{pmatrix}$$

$$O(2) = \{R_\theta S_\Psi \mid 0 \leq \theta < 2\pi, 0 \leq \Psi < \pi\}$$

The physical symmetry group of a circle is only rotations

$$SO(2) = \{R_\theta \mid 0 \leq \theta < 2\pi\}$$

D_n | Recall that D_n consisted of rotations

by $0, \frac{2\pi}{n}, \frac{4\pi}{n}, \dots, \frac{2n\pi}{n} = 2\pi$; a certain reflection, and products of these.

Abstractly, we can pick any one reflection S_Ψ and generate D_n with $R_{\frac{2\pi}{n}}$ & S_Ψ